

Contents

1	What Is Differential Geometry?	1
1.1	Cartography and Differential Geometry	1
1.2	Coordinates	3
1.3	Topological Manifolds*	7
1.4	Smooth Manifolds Defined*	9
1.5	The Master Plan	12
2	Foundations	13
2.1	Submanifolds of Euclidean Space	13
2.2	Tangent Spaces and Derivatives	21
2.2.1	Tangent Space	22
2.2.2	Derivative	26
2.2.3	The Inverse Function Theorem	28
2.2.4	Regular Values	29
2.3	Submanifolds and Embeddings	31
2.4	Vector Fields and Flows	35
2.4.1	Vector Fields	35
2.4.2	The Flow of a Vector Field	37
2.4.3	The Group of Diffeomorphisms	42
2.4.4	The Lie Bracket	42
2.5	Lie Groups	48
2.5.1	Definition and Examples	49
2.5.2	The Lie Algebra of a Lie Group	52
2.5.3	Lie Group Homomorphisms	55
2.5.4	Closed Subgroups	59
2.5.5	Lie Groups and Diffeomorphisms	64
2.5.6	Smooth Maps and Algebra Homomorphisms	66
2.5.7	Vector Fields and Derivations	68

2.6	Vector Bundles and Submersions	69
2.6.1	Submersions	69
2.6.2	Vector Bundles	71
2.6.3	The Implicit Function Theorem	76
2.7	The Theorem of Frobenius	77
2.8	The Intrinsic Definition of a Manifold*	83
2.8.1	Definition and Examples	83
2.8.2	Smooth Maps and Diffeomorphisms	88
2.8.3	Tangent Spaces and Derivatives	89
2.8.4	Submanifolds and Embeddings	91
2.8.5	Tangent Bundle and Vector Fields	93
2.8.6	Coordinate Notation	95
2.9	Consequences of Paracompactness*	97
2.9.1	Paracompactness	97
2.9.2	Partitions of Unity	99
2.9.3	Embedding in Euclidean Space	102
2.9.4	Leaves of a Foliation	108
2.9.5	Principal Bundles	109
2.9.6	Standing Assumption	115
3	The Levi-Civita Connection	117
3.1	Second Fundamental Form	117
3.2	Covariant Derivative	123
3.3	Parallel Transport	125
3.4	The Frame Bundle	132
3.4.1	Frames of a Vector Space	132
3.4.2	The Frame Bundle	133
3.4.3	Horizontal Lifts	136
3.5	Motions and Developments	141
3.5.1	Motion	141
3.5.2	Sliding	143
3.5.3	Twisting and Wobbling	145
3.5.4	Development	148
3.6	Christoffel Symbols	154
3.7	Riemannian Metrics*	160
3.7.1	Existence of Riemannian Metrics	160
3.7.2	Two Examples	162
3.7.3	The Levi-Civita Connection	163
3.7.4	Basic Vector Fields in the Intrinsic Setting	166
4	Geodesics	169
4.1	Length and Energy	169
4.1.1	The Length and Energy Functionals	169
4.1.2	The Space of Paths	172
4.1.3	Characterization of Geodesics	173

4.2	Distance	177
4.3	The Exponential Map	184
4.3.1	Geodesic Spray	184
4.3.2	The Exponential Map	185
4.3.3	Examples and Exercises	188
4.3.4	Geodesics in Local Coordinates	190
4.4	Minimal Geodesics	191
4.4.1	Characterization of Minimal Geodesics	191
4.4.2	Local Existence of Minimal Geodesics	192
4.4.3	Examples and Exercises	196
4.5	Convex Neighborhoods	199
4.6	Completeness and Hopf–Rinow	203
4.6.1	Geodesic Completeness	203
4.6.2	Global Existence of Minimal Geodesics	204
4.6.3	Proof of the Hopf–Rinow Theorem	206
4.7	Geodesics in the Intrinsic Setting*	211
4.7.1	Intrinsic Distance	211
4.7.2	Geodesics and the Levi-Civita Connection	213
4.7.3	Examples and Exercises	214
5	Curvature	217
5.1	Isometries	217
5.2	The Riemann Curvature Tensor	226
5.2.1	Definition and Gauß–Codazzi	226
5.2.2	Covariant Derivative of a Global Vector Field	228
5.2.3	A Global Formula	231
5.2.4	Symmetries	233
5.2.5	Riemannian Metrics on Lie Groups	235
5.3	Generalized Theorema Egregium	238
5.3.1	Pushforward	238
5.3.2	Theorema Egregium	239
5.3.3	Gaußian Curvature	243
5.4	Curvature in Local Coordinates*	247
5.4.1	Riemann	247
5.4.2	Gauß	248
6	Geometry and Topology	251
6.1	The Cartan–Ambrose–Hicks Theorem	251
6.1.1	Homotopy	251
6.1.2	The Global C-A-H Theorem	253
6.1.3	The Local C-A-H Theorem	259
6.2	Flat Spaces	261

6.3	Symmetric Spaces	266
6.3.1	Symmetric Spaces	266
6.3.2	Covariant Derivative of the Curvature	268
6.3.3	Covariant Derivative of the Curvature in Local Coordinates	271
6.3.4	Examples and Exercises	272
6.4	Constant Curvature	273
6.4.1	Sectional Curvature	273
6.4.2	Constant Sectional Curvature	275
6.4.3	Examples and Exercises	278
6.4.4	Hyperbolic Space	279
6.5	Nonpositive Sectional Curvature	286
6.5.1	The Cartan–Hadamard Theorem	286
6.5.2	Cartan’s Fixed Point Theorem	292
6.5.3	Positive Definite Symmetric Matrices	295
6.6	Positive Ricci Curvature*	302
6.6.1	The Ricci Tensor in Local Coordinates	303
6.6.2	The Bonnet–Myers Theorem	303
6.6.3	Positive Sectional Curvature	305
6.7	Scalar Curvature*	306
6.7.1	Definition and Basic Properties	307
6.7.2	Scalar Curvature in Local Coordinates	309
6.7.3	Positive Scalar Curvature	309
6.7.4	Constant Scalar Curvature	310
6.8	The Weyl Tensor*	312
6.8.1	Definition and Basic Properties	313
6.8.2	The Weyl Tensor in Local Coordinates	314
6.8.3	Conformal Invariance	315
6.8.4	Self-Dual Four-Manifolds	315
7	Topics in Geometry	321
7.1	Conjugate Points and the Morse Index*	321
7.1.1	Conjugate Points	322
7.1.2	The Morse Index Theorem	323
7.1.3	Locally Minimal Geodesics	328
7.2	The Injectivity Radius*	332
7.3	The Group of Isometries*	336
7.3.1	The Myers–Steenrod Theorem	336
7.3.2	The Topology on the Space of Isometries	338
7.3.3	Killing Vector Fields	341
7.3.4	Proof of the Myers–Steenrod Theorem	345
7.3.5	Examples and Exercises	354
7.4	Isometries of Compact Lie Groups*	356

7.5	Convex Functions on Hadamard Manifolds*	362
7.5.1	Convex Functions and The Sphere at Infinity	363
7.5.2	Inner Products and Weighted Flags	371
7.5.3	Lengths of Vectors	375
7.6	Semisimple Lie Algebras*	385
7.6.1	Symmetric Inner Products	385
7.6.2	Simple Lie Algebras	388
7.6.3	Semisimple Lie Algebras	392
7.6.4	Complex Lie Algebras	397
Appendix A: Notes		403
A.1	Maps and Functions	403
A.2	Normal Forms	404
A.3	Euclidean Spaces	406
References		409
Index		413